

Satellite-Based Modeling of Evapotranspiration and Uncertainties in Eddy Covariance Flux

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Outline

- I: Satellite-based Modeling of ET at Fine and Large Scales
 - 1. How does the satellite work for ET estimate?
 - 2. What is the Performance of this modeling at field scale?
- II: Uncertainty in Eddy Covariance Measurements
 - 1. Flux spatial context vs. Sensor Heights
 - 2. High frequency flux loss vs. Sensor Heights
 - 3. Low frequency flux loss vs. Sensor Heights
 - 4. WPL corrections for CO2 and N2O Flux
 - 5. Trace gas analyzer's requirements for EC

Satellite's Approach

Satellite-Based Land Surface Energy Balance:

Thermal images approach T_R for a simple or complicated relation of T_R vs. T_{AC} . Visible and infrared images are responsible for the surface radiances, NDVI, LAI, albedo, biomass, and other biophysical variables.

Models for Large Scales:

1. One-source model

- a) Surface energy balance algorithm for land (SEBAL, Bastiaanssen, et al 1998).
- b) Surface energy balance system (SESB, Su, 2003)
- c) Mapping evapotranspiration with internalized calibration (METRIC, Allen, et al., 2007).

2. Two-source model

- a) Two-source model (TSM, Norman et al., 1995).
- b) Two-source time-integrated model (TSTIM, Andersen et al, 1997 & 2007).

How does Satellite Information do for ET?

Satellite-Based Land Surface Energy Balance:

- --- Thermal images provide T_R Information.
- --- Visible and infrared images are used for calculating:
 - Spectral radiances,
 - Spectral reflectance and transmittance,
 - NDVI, LAI, albedo, biomass, and
 - Other biophysical variables.

Sensible Heat Flux:

$$\mathbf{H} = \rho \mathbf{C}_{p} \frac{\mathbf{T}_{AC} - \mathbf{T}_{A}}{\mathbf{R}_{A}}$$

Aerodynamic and Radiometric Temperatures:

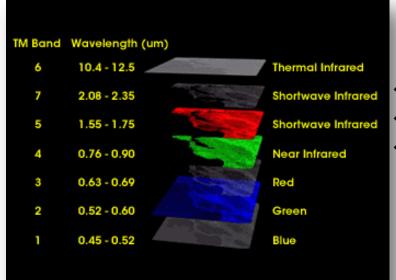
$$\textbf{T}_{\textbf{AC}} \propto \textbf{T}_{\textbf{R}}$$

Inputs: Landsat 5/7 and Weather Station/EC Tower

Discontinuous Spatial Info



Continuous Temporal Info



- All TM bands
- Calibrated pixel value [DN]
- Resampled thermal band

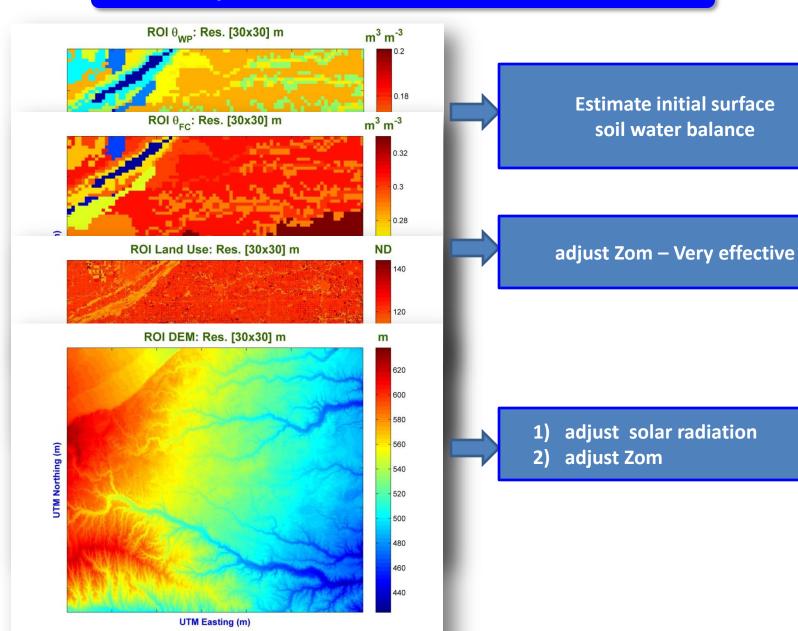
Spatial Resolution: 30x30m



- Air Temp, Air humidity
- Solar radiation, Precip.
- Wind speed and DIR

Temporal Resolution: 1 Hour

Inputs: Static Land Surface Data



Basic Computations

Spectral Radiances

$$\mathbf{L}_{\lambda} = \mathbf{G}_{\text{rescale}} \mathbf{Q}_{\text{cal}} + \mathbf{B}_{\text{rescale}}$$

$$\rho_{\mathbf{p}} = \frac{\boldsymbol{\pi} \cdot \mathbf{L}_{\lambda} \cdot \mathbf{d}^{2}}{\mathbf{ESUN}_{\lambda} \cdot \mathbf{cos} \theta_{\mathbf{S}}}$$

---Chander et al. 2009.

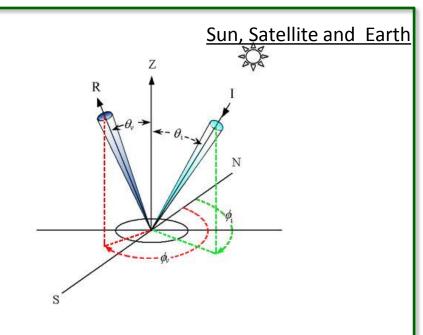
Surface Scalar Quantities

$$T_{R} = \frac{K_{2}}{\ln\left(\frac{\varepsilon_{NB}K_{1}}{R_{c}}\right) + 1}$$

NDVI =
$$\frac{\rho_{(x,y,4)} - \rho_{(x,y,3)}}{\rho_{(x,y,4)} + \rho_{(x,y,3)}}$$

$$\alpha = \int\limits_{b=1}^{7}\! \rho_{s,b} w_b db$$

---Allen et al. 2007.



Surface Available Energy

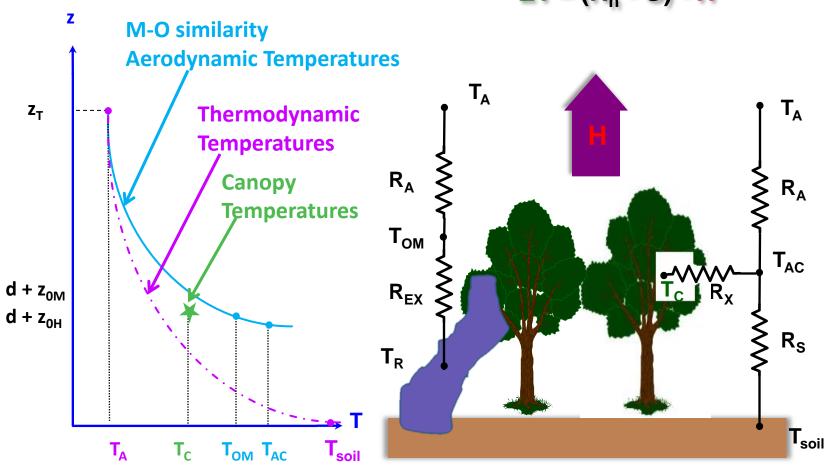
$$\boldsymbol{R}_{n} = (1-\alpha)\boldsymbol{R}_{s} \boldsymbol{\downarrow} + \boldsymbol{\epsilon}_{a}\boldsymbol{\sigma}\boldsymbol{T}_{a}^{4} - (1-\boldsymbol{\epsilon}_{s})\boldsymbol{\epsilon}_{a}\boldsymbol{\sigma}\boldsymbol{T}_{a}^{4} - \boldsymbol{\epsilon}_{s}\boldsymbol{\sigma}\boldsymbol{T}_{s}^{4}$$

$$\frac{G}{R_n} = (T_R - 273.15)(0.0038 + 0.0074\alpha - 0.98NDVI^4)$$

---Bastiananssen et al. 2000.

Key Computations in Modeling

$$ET = (R_n - G) - H$$



$$\mathbf{R}_{\mathsf{EX}} = \left[\sum_{i=1}^{6} \mathbf{a}_{i} \mathbf{LAI}^{i}\right] u_{*}^{-1}$$

Iterative Estimate of Sensible Heat

$$R_{A} = \frac{[ln(\frac{z_{U}-d}{z_{OM}}-\psi_{M})][ln(\frac{z_{T}-d}{z_{OM}}-\psi_{H})]}{k^{2}U}$$

$$R_{\chi} = \frac{180}{LAI} (\frac{L_{w}}{U_{d+z_{om}}})^{0.5}$$

$$R_{s} = \frac{1}{a(T_{s} - T_{c})^{\frac{1}{3}} + bU_{s}}$$

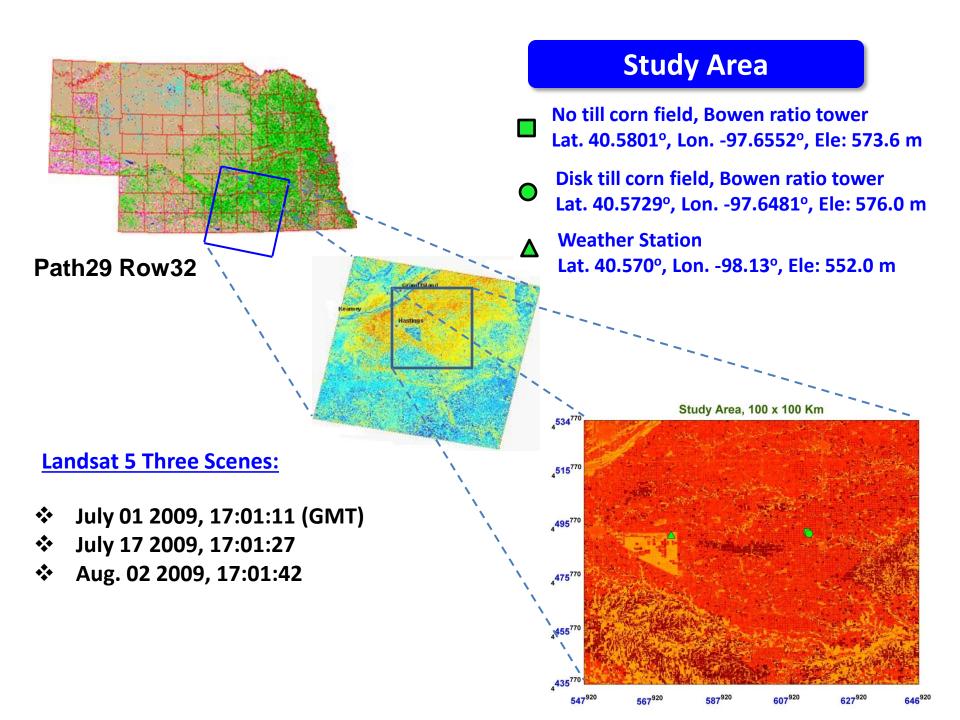
$$\boldsymbol{T}_{\!\mathsf{R}} = \boldsymbol{f}_{\!\mathsf{c}}\!\left(\boldsymbol{\phi}\right)\!\boldsymbol{T}_{\!\mathsf{C}} + \!\left(1\!-\!\boldsymbol{f}_{\!\mathsf{c}}\!\left(\boldsymbol{\phi}\right)\!\right)\!\boldsymbol{T}_{\!\mathsf{S}}$$

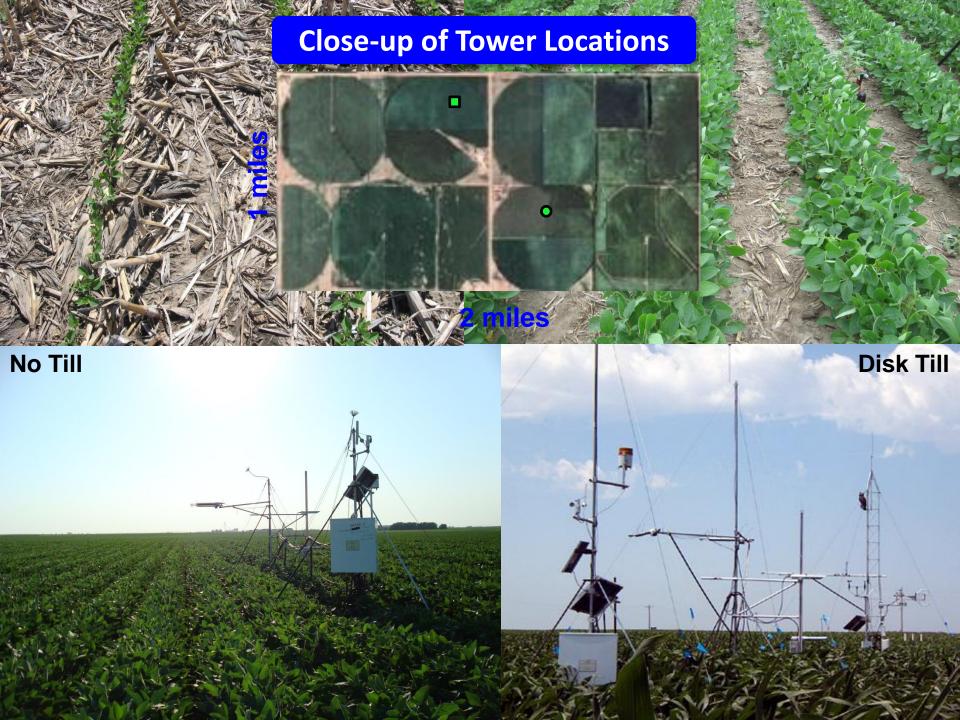
$$\mathbf{H_{C}} = \boldsymbol{\rho} \boldsymbol{C_{p}} \, \frac{\boldsymbol{T_{C}} - \boldsymbol{T_{AC}}}{\boldsymbol{R_{X}}}$$

$$H_{s} = \rho C_{p} \frac{T_{s} - T_{AC}}{R_{s}}$$

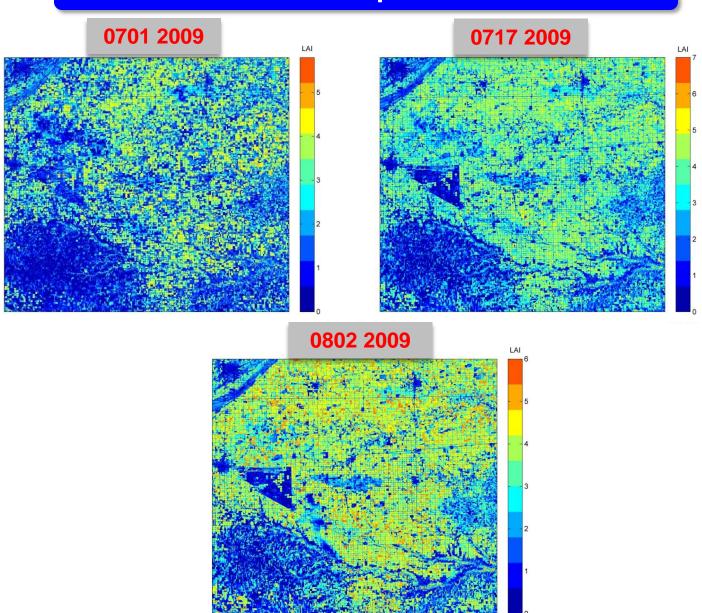
$$H = H_C + H_S = \rho C_p \frac{T_R - T_A}{R_A + R_{EX}}$$

$$ET = (R_n - G) - H$$



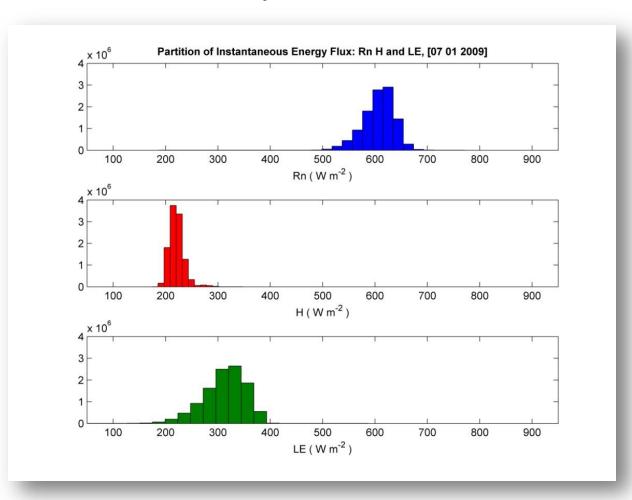


Scalar Outputs: LAI



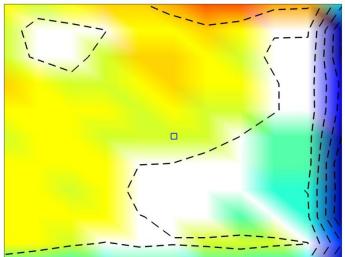
Scalar Flux Outputs

July 1st 2009

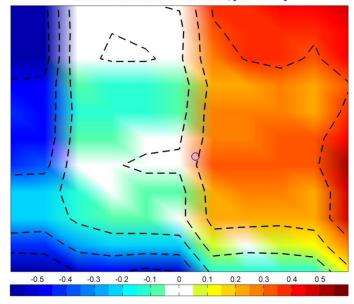


Validation: Daily ET [300 x 300m] for No Till vs. Disk Till



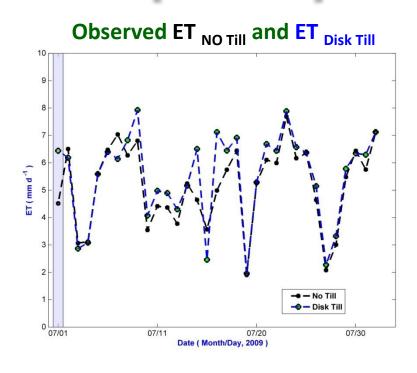


Disk Till: Field Mean ET = 6.7 mm d¹, [0701 2009]



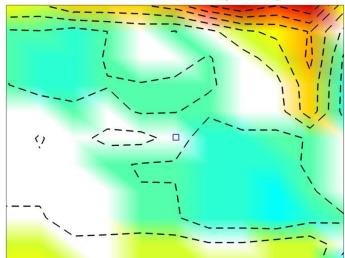
Variations from the Field Mean (mm d -1)

[0701 2009]

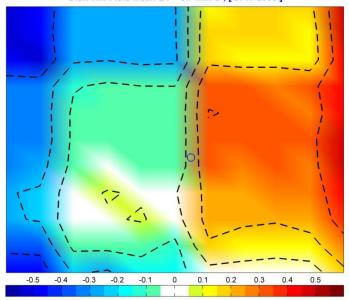


Validation: Daily ET [300 x 300m] for No Till vs. Disk Till



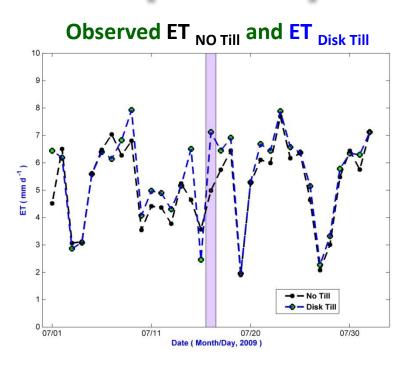


Disk Till: Field Mean ET = 5.7 mm d¹, [0717 2009]



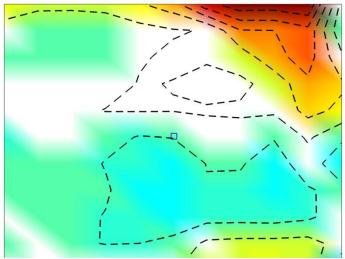
Variations from the Field Mean (mm d -1)

[0717 2009]

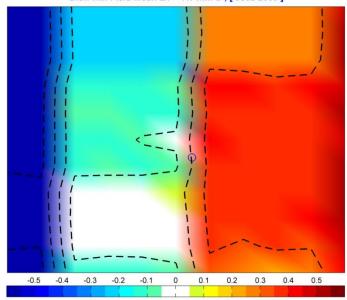


Validation: Daily ET [300 x 300m] for No Till vs. Disk Till



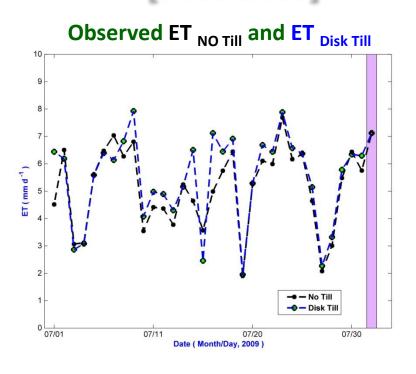


Disk Till: Field Mean ET = 7.7 mm d¹, [0802 2009]



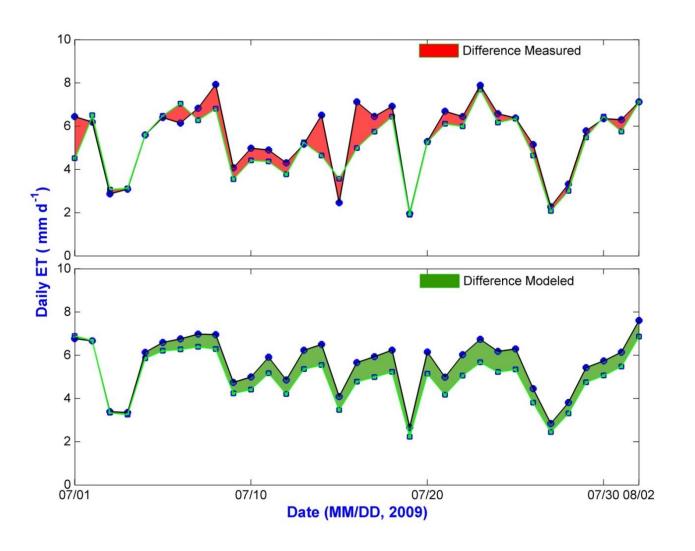
Variations from the Field Mean (mm d -1)

[0802 2009]

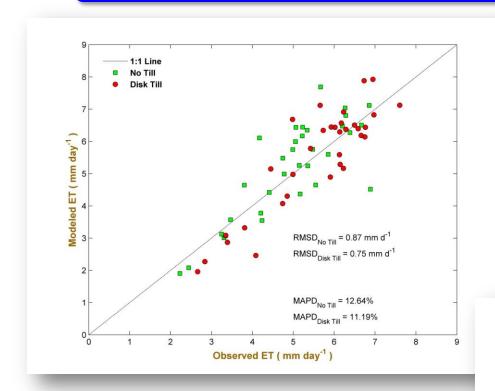


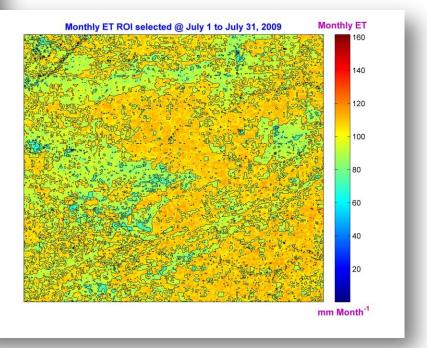
Comparison of Daily ET

Measured Difference (top) and Modeled Difference (Bottom) between No Till (□) and Disk Till (○) Field



Modeling Performance and Monthly Spatial ET Estimate





Summary: ET Modeling

A modified surface energy balance model was developed. Models were performed well under both large scale [100 x 100 Km] and field scale --- R_{FX} and LU data Introduced.

Automated searching, locating, and estimating the endpoints of the hot and cold pixels made selection objective with less assumptions --- Automatic & Robust.

The models used have been designed to be robust to expected errors (around 12%) for daily ET validated by the point-measurements from Bowen ratio systems.

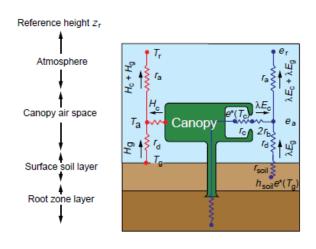
The field scale ET variations presented here suggest that disk till corn field had significantly and consistently larger ET than the no till corn fields in July 2009.

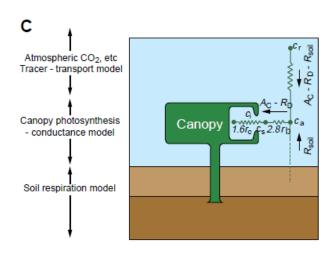
Mapping Tool: only four inputs

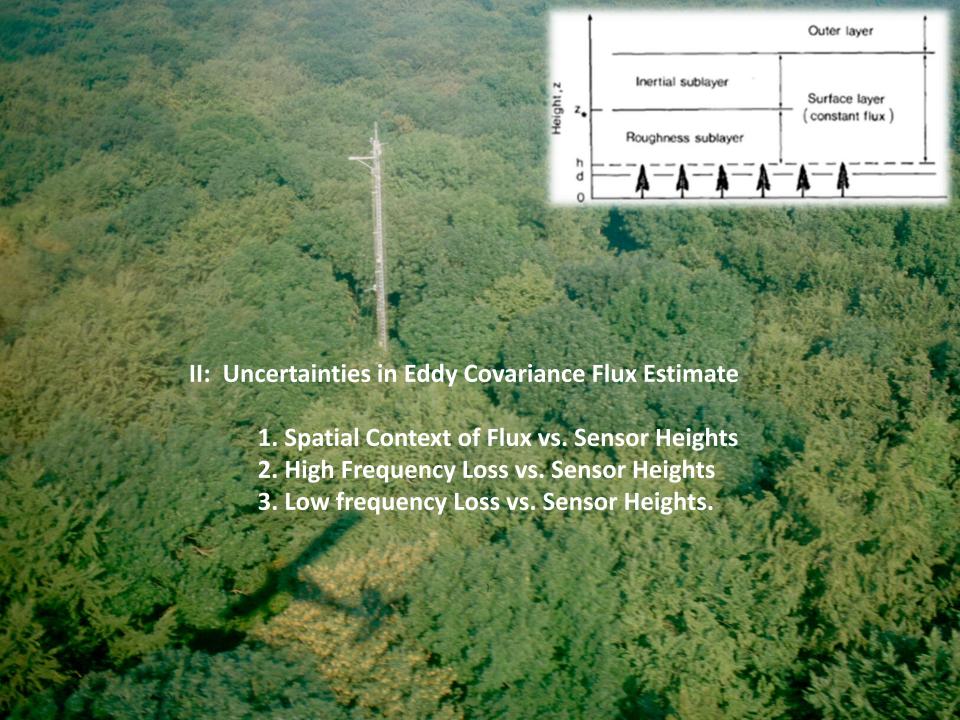
```
% OSM modeling and mapping ET
2
       % This program is a research code for calculating ET by using satellites of
3
       % Landsat 5 and 7 as well as local whether station information. It is
5
       % workable under current condition when your selected ROI is apopporiate
       % but WITHOUT ANY WARRANTY for your application purposes.
       % Time: Jan. 2007 started up and continuted in July 2009 at the UNL
8
9
       % Status: Workable
10
       % Author: Xiaomao Lin @ UNL
11
       % Revision: 07 27 2009: it was working
12
                  08 03 2009: Optimalized pixel selection algorithm (Dry and Wet)
13
                  08 03 2009: Fixed dT algorithm
14
                  08 2009: Added the landuse and DEM
15
                  08 2009: Comparison confirmed with Ian
16
                  09 2009: Final comparison done
17
                  09 2009: Optimized the codes
18
                  01 2010: Comparison re-confirmed with Towers
                  02 2010: OK status with
19
       clear all; clc; close all;
21
22
       % Step 1: INPUTS for OSM: 4 input groups
23
24
       % Weather data is the mat format already inclduing HD st ed lat lon ele
       % HD contains 9 variables (see STNbasicINFO.m) inside
25
26
       % 1.1 Weather station Info
                                                                              Input I
27 -
       STNPATHandName = 'd:\mat\et pm\matdata\Claycenter2005 9hr';
       ~ **********
28
29
       % 1.2 Input sat image file
       £ ********************
30
                                                                               Input II
31 -
       SATimPATHandName= 'd:\sat data center\L5029032 03220090701 B';
       $SATimPATHandName = 'd:\sat data center\L5029032 03220090717 B';
32
33
       $SATimPATHandName= 'd:\sat data center\L5029032 03220090802 B';
34
       % 1.3 Input landuse and land cover info
                                                                                Input III
35 -
       LULCimPATHandName = 'd:\sat data center\Landuse p29r32 2005.tif';
       DEMimPATHandName = 'd:\sat data center\dem 30m p29r32 float.tif';
37
       % 1.4 Input soil property info
38
       %DEMimPATHandName = 'd:\sat data center\dem 30m p29r32.tif';
                                                                                 Input IV
39 -
       SOILfcPATHandName = 'd:\sat data center\fc fraction p29r32 30m.tif';
40 -
       SOILwpPATHandName = 'd:\sat data center\wp fraction p29r32 30m.tif';
       %LULCimPATHandName = 'd:\sat data center\jly2009\landuse 2005 pwgs84.tif';
41
       %DEMimPATHandName = 'd:\sat data center\jly2009\p29r32 051905 dem 30m wgs84 float.tif';
42
43
       %SOILfcPATHandName = 'd:\sat data center\jly2009\fc fraction p29r32 30m.tif|';
       %SOILwpPATHandName = 'd:\sat data center\jly2009\wp fraction p29r32 30m.tif|;
44
45
```

References

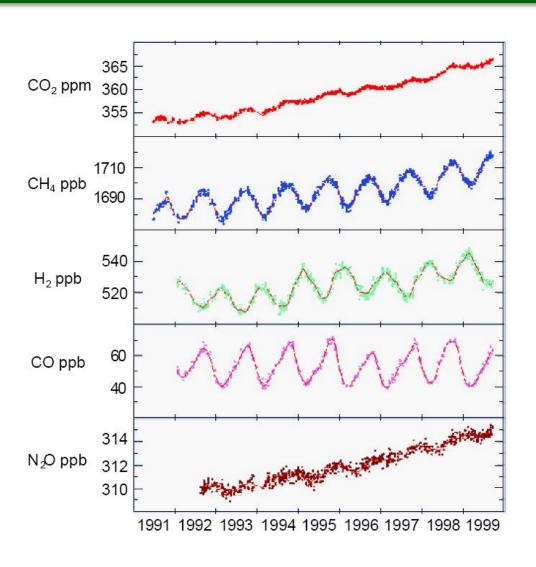
- 1. P. J. Sellers et al, 1995, Science
- 2. John Norman et al, 1995, AFM
- 3. James Wallance, 1995, AFM
- 4. Shuttleworth and Wallace, 1985







Why EC Fluxes of Trace Gas are Important?



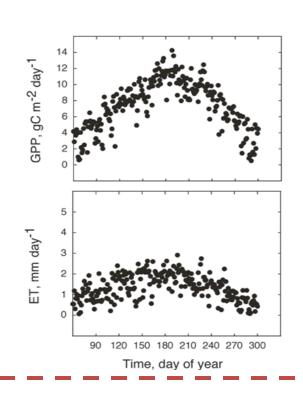
Eddy Covariance: From Measurements to Fluxes



$$H = \rho c_p \overline{w'T'}$$

$$LE = \lambda \overline{w'q'}$$

$$F_c = \overline{w'c'}$$



- u v w, and T_{sonic}
- H₂O and CO₂ (IRGA)
- Pressure
- Mean T_a and RH_a
- Diagnostic Status

Data Processing

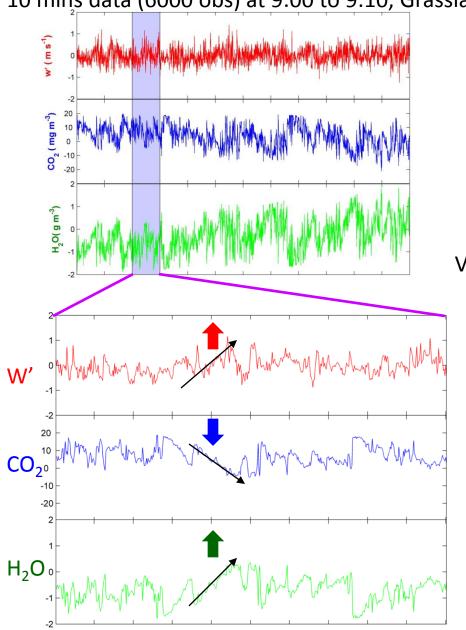
- Fc (carbon flux)
- LE (water flux)
- Hs (sensible heat flux)

Eddy Size (Limited Bandwidth)

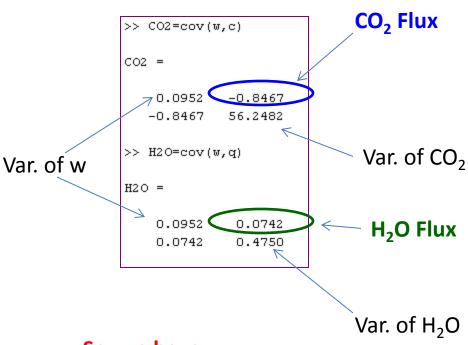
0.000556 Hz (30 mins)

What is the Eddy Covariance in a simple way?

10 mins data (6000 obs) at 9:00 to 9:10, Grassland



$$Cov(w,c) = E[(w-\overline{w})(c-\overline{c})] = E[w'c']$$



So, we have

$$CO_2$$
 Flux = -0.8467 m s⁻¹ mg m⁻³ = -0.8467 mg m⁻² s⁻¹

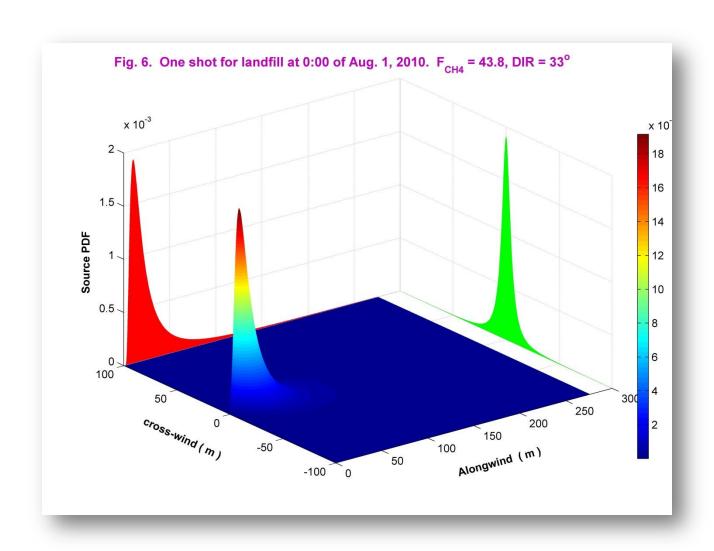
$$H_2O$$
 Flux = 0.0742 m s⁻¹ g m⁻³
= 0.0742 g m⁻² s⁻¹
= 176.4 W m⁻²

The Juice of the Eddy Covariance

Start from mass conservation equation (CO2, or H2O) or Navier-Stokes equation, then, apply Reynolds decomposition and averaging, along with the turbulent continuity equation in the x-z planes, it will lead to:

$$\begin{split} F_{v} &= L_{v} \, \overline{w' \rho_{v'}} \Big|_{h_{m}} \\ &= \underbrace{\int_{0}^{h_{m}} L_{v} \frac{\partial \overline{\rho_{v}}}{\partial t} dz}_{F_{v}^{ST}: \, Storage} + \underbrace{\int_{0}^{h_{m}} L_{v} \left(\overline{u} \frac{\partial \overline{\rho_{v}}}{\partial x} \right) dz}_{F_{v}^{HA}: \, Hori. \, Adv} + \underbrace{\int_{0}^{h_{m}} L_{v} \left(\overline{w} \frac{\partial \overline{\rho_{v}}}{\partial z} \right) dz}_{F_{v}^{VA}: \, Vert. \, Adv} \end{split}$$

An Example of Scalar Footprint Analysis Footprint Context



Spectral Attenuation of Scalar Flux

$$\langle \mathbf{w'c'} \rangle = \int_0^\infty \mathbf{Co}_{\mathbf{wc}} (\mathbf{f}) d\mathbf{f}$$

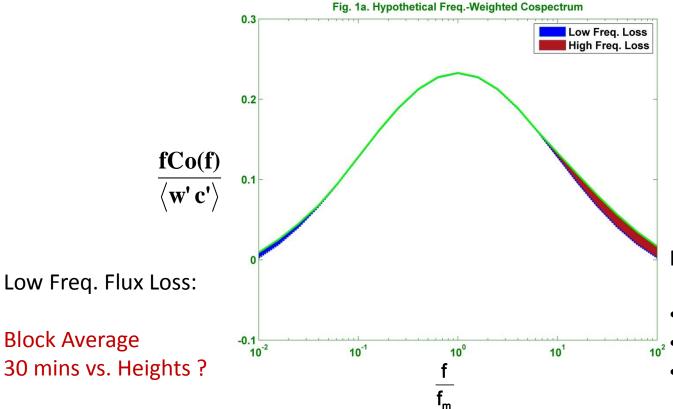
$$\langle \mathbf{w'c'} \rangle_m = \int_0^\infty \mathbf{H_c(f)Co_{wc}(f)df}$$

Cospectrum model:
$$\frac{fCo_{wc}(f)}{\langle w'c' \rangle} = \frac{2}{\pi} \frac{f/f_m}{(1 + (f/f_m)^{\mu})^{\alpha}}$$

Spectral correction:
$$\frac{\left\langle w'c'\right\rangle_{m}}{\left\langle w'c'\right\rangle} = \frac{1}{1+\left(2\pi\,f_{m}\,\tau_{c}\right)^{\alpha}}\frac{\left(2\pi\,f_{m}\,\tau_{b}\right)^{\alpha}}{1+\left(2\pi\,f_{m}\,\tau_{b}\right)^{\alpha}}$$

- I: a single-pole, low-pass RC filter for all path average, displacement, and other high-freq.
- II: block average considered as a high-pass filter if assume the $\tau_b = T_B / 2.8$ (Kaimal, 1989).

Cospectra Models for EC Flux Corrections

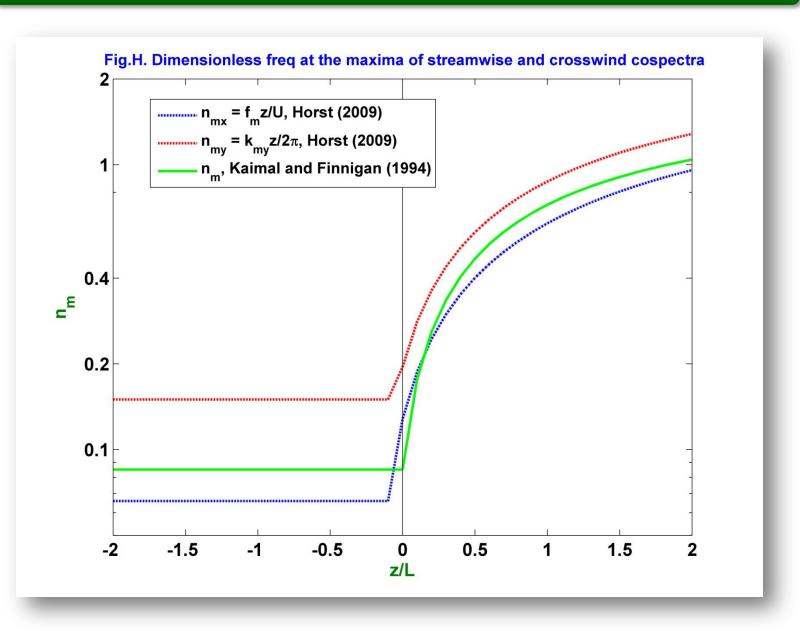


Block Average

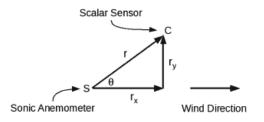
High Freq. Flux Loss:

- Path average?
- Time Response?
- Tube attenuation (if CP)?
- Sensor Displacement?

A Key in Spectral Models: Maxima (f_m or n_m) of Cospectra



Sensor Displacement: High Freq. Flux Loss Vs. Heights



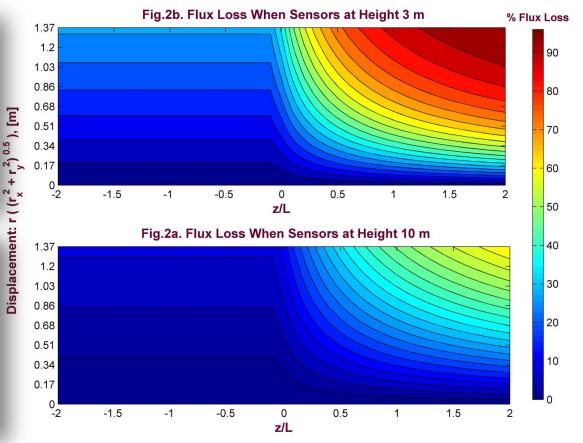
$$\frac{F(r_{x}, r_{y})}{F_{0}} = \exp\left[-(\ln^{2} Ax + \ln^{2} Ay)^{1/2}\right]$$

$$Ax = \exp(-\frac{2\pi}{z}n_{mx})$$
 $Ay = \exp(-\frac{2\pi}{z}n_{my})$ - Horst and Lenschow, 2009. BLM

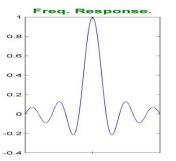
$$Ay = \exp(-\frac{2\pi}{z}n_{my})$$



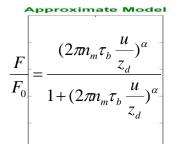




Block Average: Low Freq. Flux Loss vs. Heights



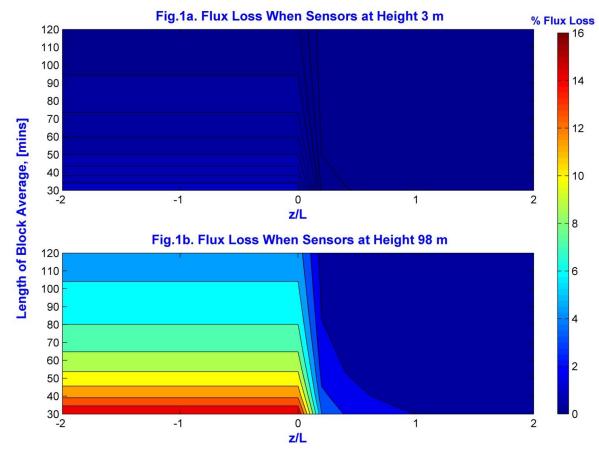




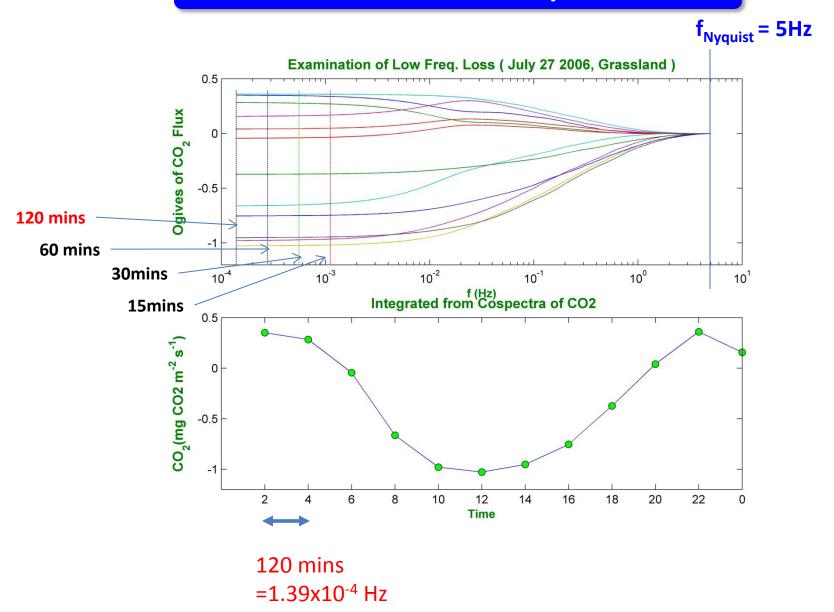
$$\tau_b = \frac{T_B}{2.8}$$

- Modified from Massman 2000 . AFM.

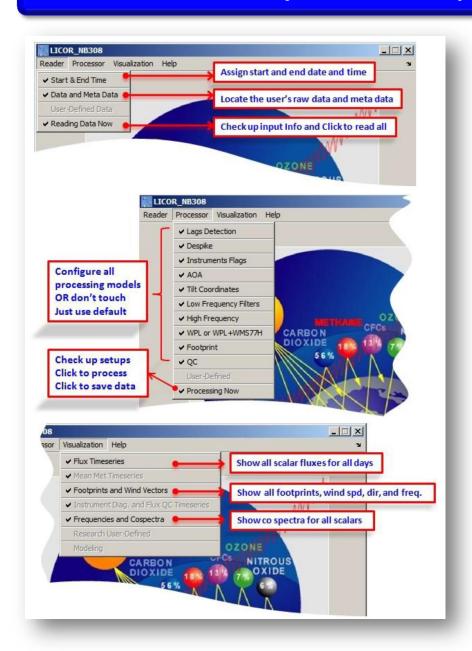


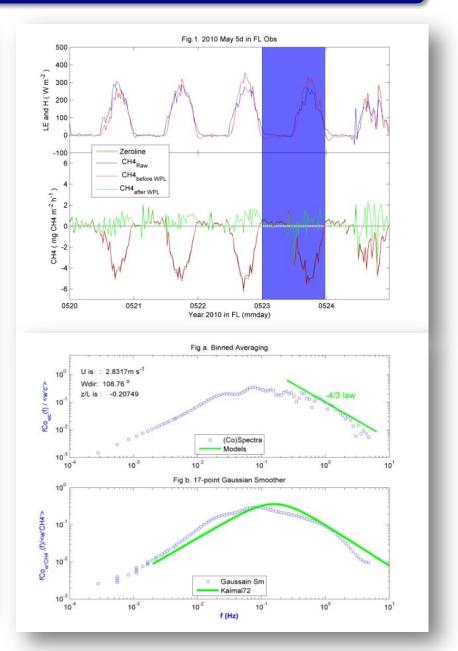


Visualization of Low Freq. Flux Loss

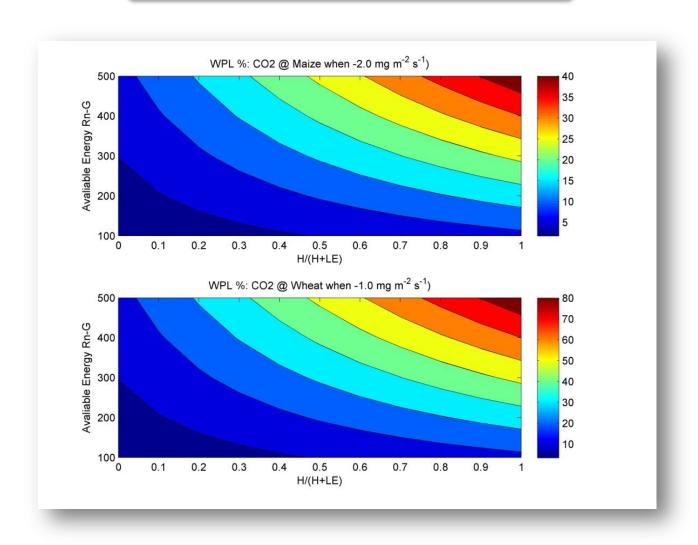


EC Software for Ecosystem Flux Computation, Analysis, and Visualization

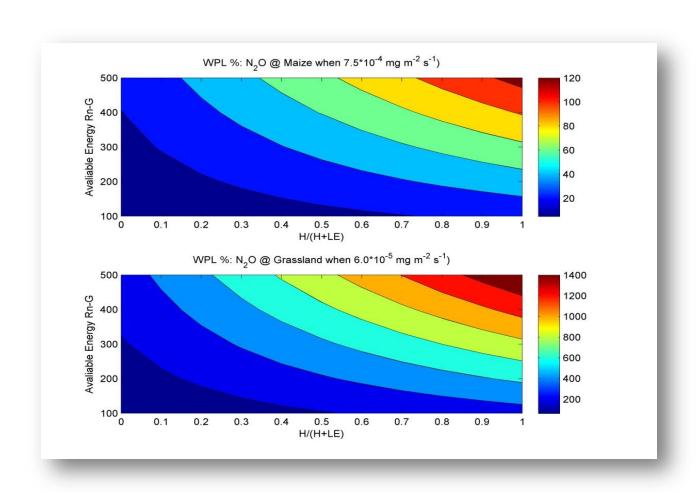




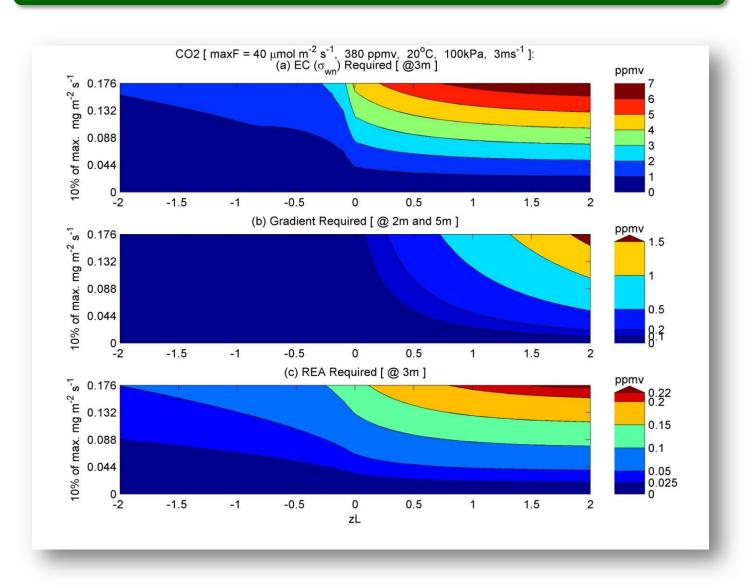
WPL for CO2 Flux



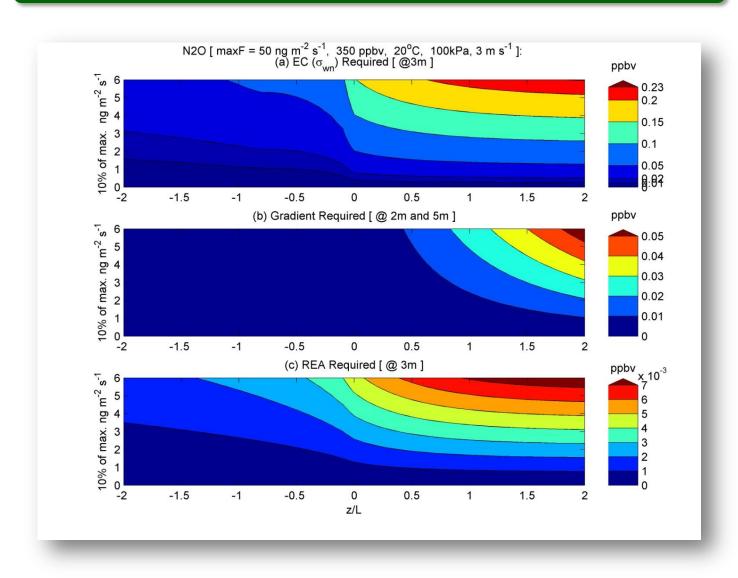
WPL for N2O Flux



Analyzer's Requirement for CO2 Flux

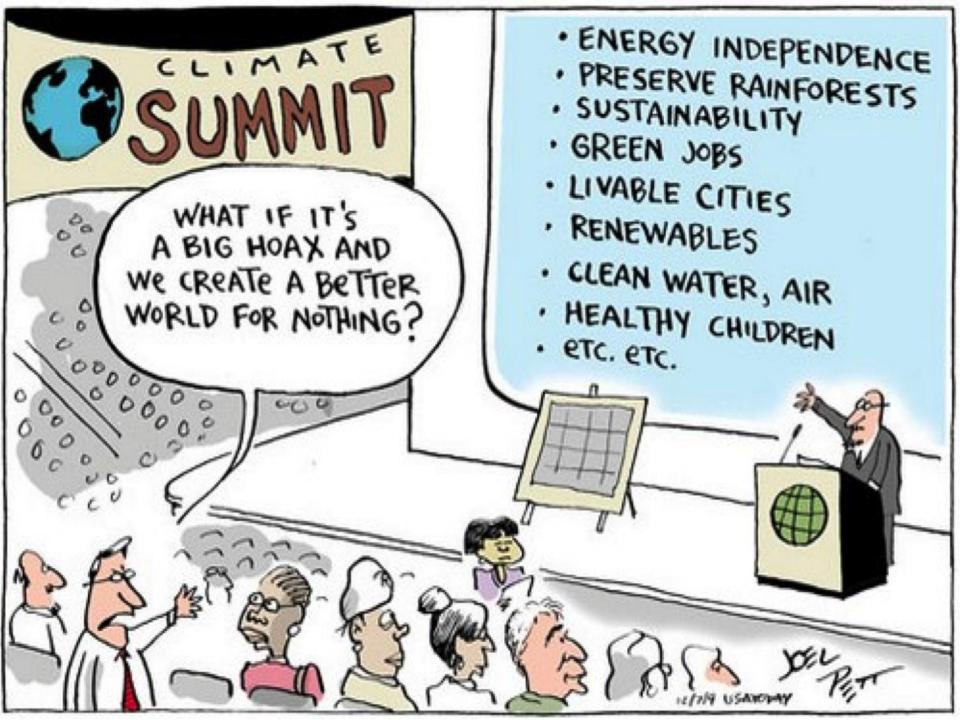


Analyzer's Requirement for N2O Flux



Recent Experiments from 2011 to 2013

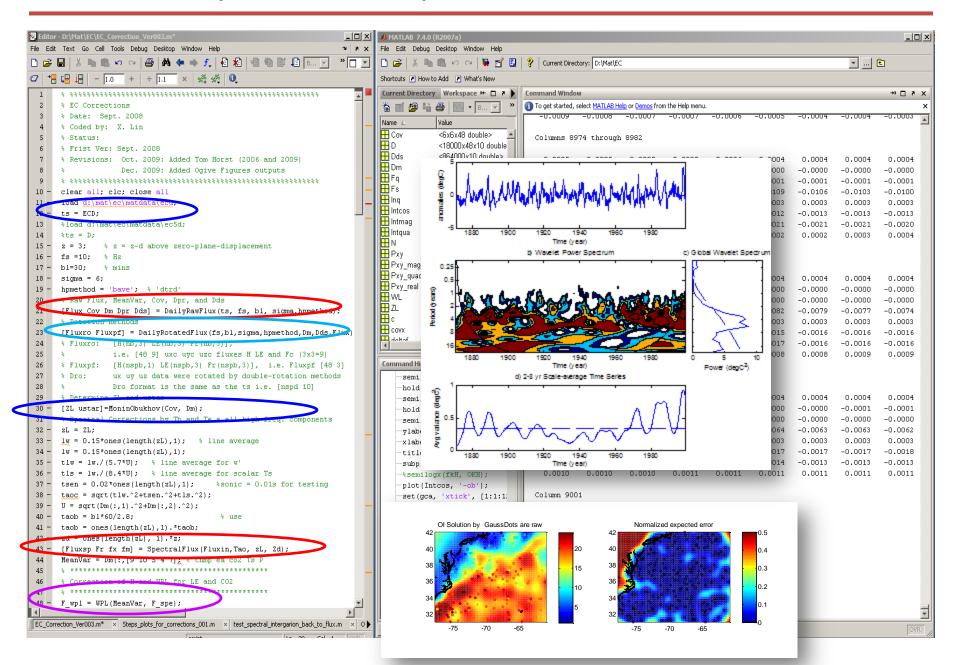








Models Implemented and Improved: EC Corrections and Visualizations



How does Satellite Information do for ET?

Satellite-Based Land Surface Energy Balance:

- --- Thermal images provide T_R Information.
- --- Visible and infrared images are used for calculating:
 - Spectral radiances,
 - Spectral reflectance and transmittance,
 - NDVI, LAI, albedo, biomass, and
 - Other biophysical variables.

Sensible Heat Flux:

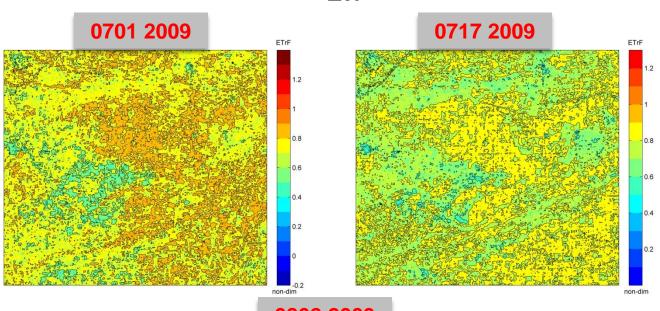
$$H = \rho C_p \frac{T_{AC} - T_A}{R_A}$$

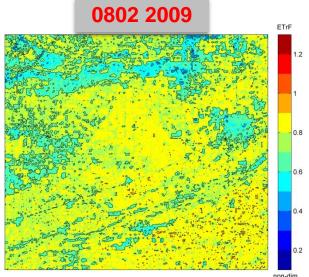
Aerodynamic and Radiometric Temperatures:

$${
m T_{AC}} \propto {
m T_{R}}$$

Fraction of Reference ET (ETrF)

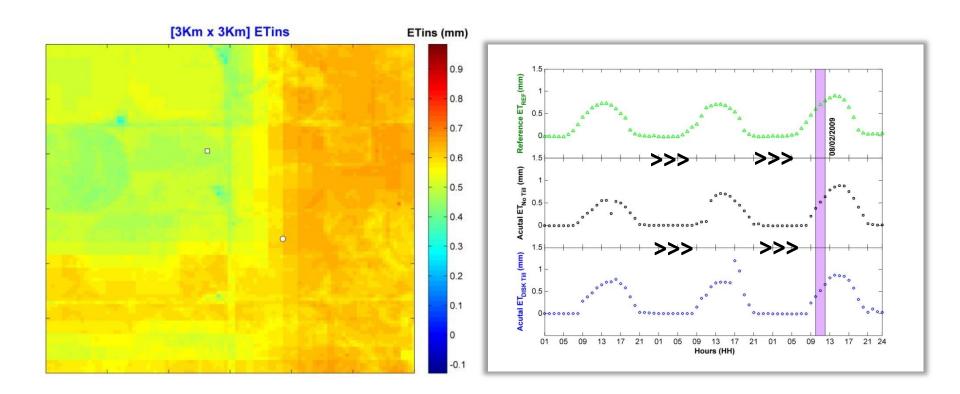






Hourly ET

[08 02 2009]



Modeled ET at Corn Fields

Observed ETr , $ET_{NO \ Till}$, $ET_{DISK \ Till}$

Key Parameterization

For major crop lands:

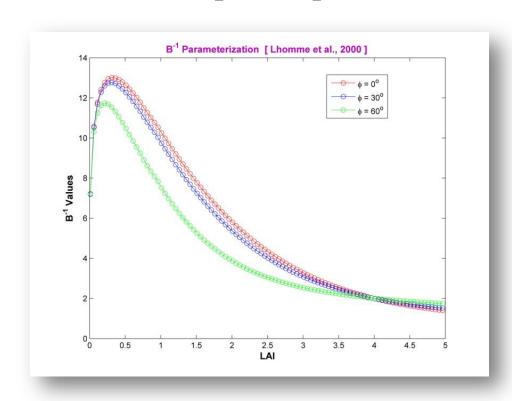
$$Z_{OM} = \frac{h_{c} - d}{exp(\frac{ku_{h_{c}}}{u_{\star}} - \psi_{H})}$$

$$\mathbf{z}_{\mathsf{OH}} = \frac{\mathbf{z}_{\mathsf{OM}}}{\mathsf{exp}(\mathsf{kB}^{-1})}$$

For non crop lands:

$$Z_{OM} = exp[a_1 NDVI + b_1]$$

$$\mathbf{R}_{\mathsf{EX}} = \left[\sum_{i=1}^{6} \mathbf{a}_{i} \mathsf{LAI}^{i}\right] u_{*}^{-1}$$

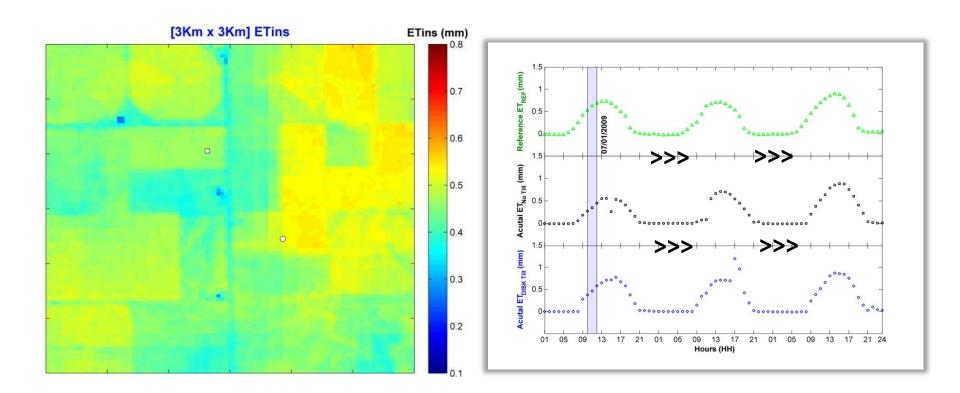


Lhomme et al. 2000

 ϕ = 0 for Landsat TM sensors

Hourly ET

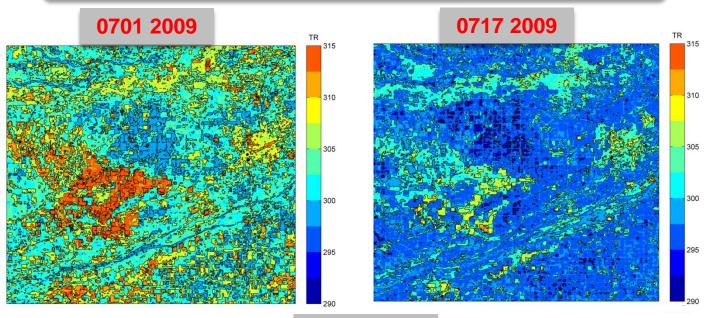
[07 01 2009]

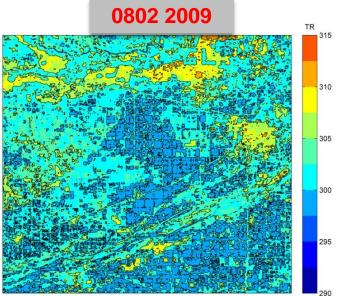


Modeled ET at Corn Fields

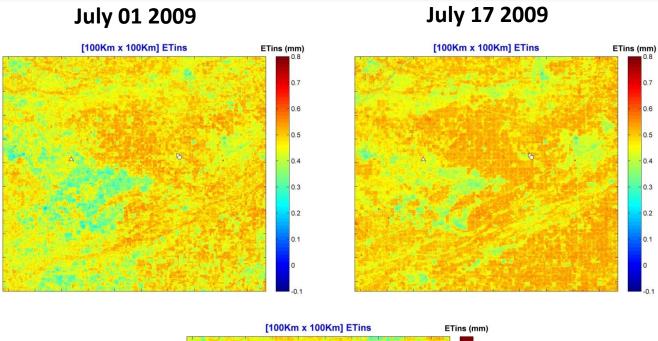
Observed ETr , $ET_{NO \ Till}$, $ET_{DISK \ Till}$

Scalar Outputs: T_R



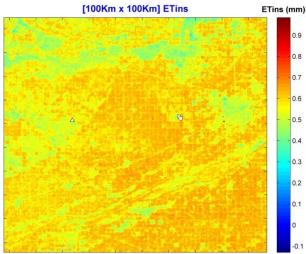


Midday Instantaneous ET as an Average of Daily ET



0.5

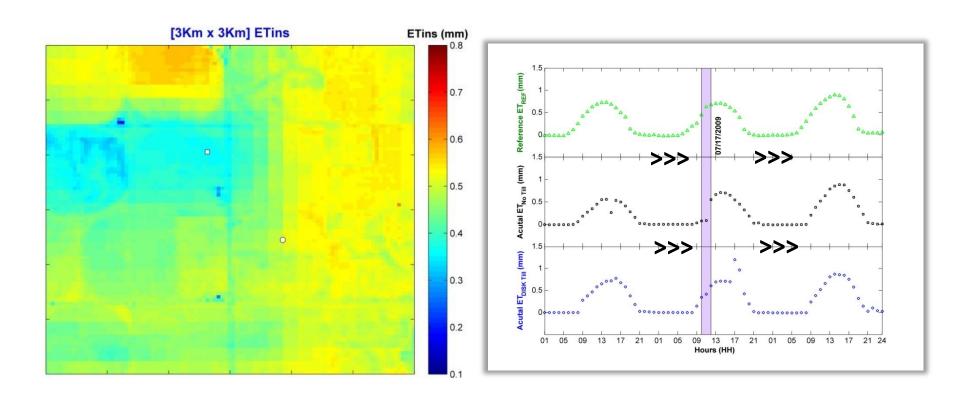
0.3



Aug. 02 2009

Hourly ET

[07 17 2009]



Modeled ET at Corn Fields

Observed ETr , $ET_{NO\ Till}$, $ET_{DISK\ Till}$

Uncertainty in EC Fluxes

raw: after despike (outlier removed).

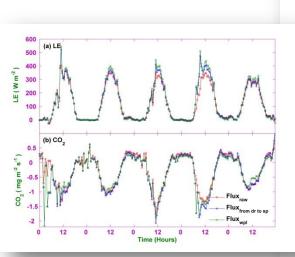
spectral: low and high freq. loss.

dr: Double rotations (v_bar and w_bar = 0).

wpl: Web correction (H and LE)

pf: Planar-fit method for rotation (5d).

H_{Ie}: Corrected H only by the LE.



Aug. 1-5, 2006. Grassland

